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# Baited-camera observations of deep-sea megafaunal scavenger ecology on the California slope

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ABSTRACT: Baited cameras have offered much insight into the ecology of scavenging animals in several parts of the worlds' oceans, revealing patterns of vertical zonation, trends in size and abundance with depth, and aspects of feeding behavior. It is surprising, then, that very little has been published on the scavenging community off the eastern Pacific continental slope, where work of this nature originated. Here we present a study of megafaunal scavenger ecology encompassing a wide range of taxa from shelf to abyssal depths off central California. During 13 baited camera deployments from 105 to 3144 m, we photographed 25 scavenging taxa, consisting mainly of fish and crabs. Combined with trawl results, these data showed that prevalence of scavenging in fishes increased from 2% of all species at 100 m to 46% of all species at 3000 m, suggesting more opportunistic feeding habits and the increasing importance of carrion as a food source at greater depths. Of 4 scavenging fish species examined, 3 (Antimora microlepis, Albatrossia pectoralis, and Anoplopoma fimbria) displayed significant increases in length with increased depth while Coryphaenoides acrolepis displayed an opposite, 'smaller-deeper' trend. Estimates of fish density generated from camera first arrival times and trawl data were compared, yielding no significant correlation. During one camera deployment, C. armatus was used as bait, which resulted in the complete absence of C. armatus, while a peak abundance of 11 individuals was observed at similar depths/locations using nonmacrourid bait. The depth-related patterns in scavenger species richness and intraspecific size-depth trends differ from those in the North Atlantic, suggesting that further regional comparisons are needed to better understand scavenger ecology on a global scale.

KEY WORDS: Scavenger · Deep sea · Size trends · Abundance estimate · Baited camera

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# INTRODUCTION

Megafaunal scavengers comprise a ubiquitous component of life in the deep sea. From invertebrates to elasmobranchs, scavengers of all sizes fulfill an important ecological function by dispersing and remineralizing large food falls that reach the seafloor and, in turn, enhancing the surrounding particulate and dissolved organic matter pool (Stockton & De Laca 1982, Smith 1985, Priede et al. 1991, Drazen et al. 2008). Scavengers are active foragers of carrion (Britton & Morton 1994). Accordingly, scavenger studies have primarily utilized baited experiments mainly with cameras—for data collection (Bailey et al. 2007). Baited camera work originated in California with the 'monster camera' (Isaacs 1969, Isaacs & Schwartzlose 1975); surprisingly however, a quantitative community-wide scavenger study along the continental margin of this region has yet to emerge. Sampling effort in this area has mainly focused on single species and targeted abyssal depths (Priede et al. 1990, 1991, 1994, 2003). Elsewhere, scavenger ecology of the continental rise and abyssal plains of the NE Atlantic has been well described in studies that focused predominantly on ichthyofauna. As a result, substantial information has been published on the composition, abundance, feeding behavior, and size distribution of scavenging fish in the NE Atlantic at depths >2000 m (Armstrong et al. 1992, Priede et al. 1994, King et al. 2006).

While attention in scavenger studies has focused on the deeper end of continental margins, limited data are available for shallower areas and for invertebrates. Scavenging represents an important foraging strategy for many animals living at shelf and slope depths (Drazen et al. 2001, Yau et al. 2002, Collins et al. 2005, Yeh & Drazen 2009) yet ecological data on scavenging communities from these regions of the world's continental margins remain sparse. Several commercially exploited scavenging species inhabit this depth range, such as the red king crab Paralithodes camtchaticus, Patagonian toothfish Dissostichus eleginoides, and Atlantic hagfish Myxine glutinosa. As fisheries extend further offshore into deeper water (Morato et al. 2006) scavenging species are likely to become increasingly exploited. An improved understanding of scavenger ecology and abundance at these depths is warranted, not only because of the current lack of existing data, but also to help guide management of future potential deep-sea stocks that are especially susceptible to overfishing (Devine et al. 2006).

Baited cameras offer an alternative method of estimating fish abundance to the traditional metric of trawl sampling. This approach may be advantageous when the latter is not possible due to bottom terrain, limitations in shiptime, or when non-extractive, low-impact sampling is desired. Priede et al. (1990) proposed a model that estimates fish density (ind. km<sup>-2</sup>) at a camera deployment based on the current speed ( $V_c$ ), swimming speed of the fish  $(V_{\rm f})$ , and the time of arrival of the first fish after touchdown, or first arrival time  $(t_0)$ . Since then, estimates of abyssal fish density based on  $t_0$  data have been widely published (Priede et al. 1994, Yau et al. 2001, King et al. 2006, King & Priede 2008, Jamieson et al. 2009), however the accuracy of these estimates in comparison to trawl data has only been evaluated on one occasion (Priede & Merrett 1996). Stock assessment is an integral step in establishing management guidelines for any fishery and can benefit from abundance data gleaned from baited cameras. Before baited camera-derived abundance estimates can be used with confidence, however, the model's accuracy needs to be validated by comparing results with independent methods of density estimation (i.e. towed camera surveys, submersible transects, trawling).

Scavengers in the deep sea rely primarily on olfaction to detect and locate food falls, as evidenced by observations of fish usually arriving from down current (Smith 1985) and by the large brain areas of abyssal fishes dedicated to smell and taste (Wagner 2001). It follows that scavenger response to baited experiments should be influenced by the type of bait being used, which for the most part has consisted of scombroid fishes (Priede et al. 1990, Henriques et al. 2002, Yeh & Drazen 2009). Barry & Drazen (2007) made opportunistic observations on the effect of introducing macrourid carrion on scavenger behavior when individuals of *Coryphaenoides armatus* died during caged experiments. Numbers of *Pachycara* sp. and *Benthoctopus* sp. increased following the death of caged *C. armatus* (introduction of macrourid carrion), however, the opposite was true for free ranging *C. armatus* whose presence at the experiment was reduced to just a few occurrences. Bait type is very likely to affect both the reaction of scavengers to bait — potentially altering  $t_0$ derived abundance estimates — and the composition of the scavenging community. This has been the reason for using standardized bait across studies; however, this approach has also precluded an evaluation of the variability in scavenger response based on bait type.

The relationship between size and depth in fishes is a topic that has produced confounding results. Heinke (1913) made early observations in the North Sea of what is now known as the 'bigger-deeper' phenomenonincreased fish size with increased depth. Since then studies have both corroborated these findings in the deep sea (Polloni et al. 1979, Macpherson & Duarte 1991) and found the opposite trend — 'smaller-deeper' (Stefenescu et al. 1992, Moranta et al. 2004). Conflicting results have even been reported for the same species (Antimora rostrata; Collins et al. 2005, King et al. 2006) and from similar regions (NW Mediterranean; Macpherson & Duarte 1991, Stefenescu et al. 1992). These differences have been attributed to feeding mode, life histories, and sampling methods of the fishes studied (Snelgrove & Haedrich 1985, Collins et al. 2005, Yeh & Drazen 2009). Perhaps the only clear result that has emerged is that no single relationship between size and depth prevails across all species, communities, regions, and depth strata. As more information on size-depth distributions is gathered, generalizations of depth related size trends will be become easier to formulate.

Here we present baited camera observations in conjunction with data collected with other methods of sampling to improve our understanding of scavenger ecology across a wide range of taxa spanning the entire California slope. Our objectives were (1) to describe the megafaunal scavenging assemblage from 100 to 3000 m in terms of composition, vertical distribution, and relative abundance, (2) to compare camera and trawl derived estimates of fish density, (3) to investigate size-depth relationships in scavenging fishes, and (4) to examine the effect of using macrourid bait on scavenging behavior.

# MATERIALS AND METHODS

**Data collection.** The deep-sea scavenging community of Monterey Bay off the central coast of California, USA (Fig. 1), was studied using a free-vehicle, timelapse camera following the design presented by Yeh & Drazen (2009). This system utilizes a 4.0 Mpx digital still camera and strobe (Scorpio Plus, Insite Pacific) suspended 2 m above the seafloor to photograph animals attracted to bait. Bait in this study consisted of one 1 to 2 kg fish (*Chanos chanos*) per deployment and was chosen based on availability and size homogeneity. All baits were defrosted and scored prior to deployment to enhance dispersal of the odor plume. Images were taken at 2 min intervals to maximize the amount of data that could be collected in a 24 h period. A current meter (Aquadopp, Nortek) mounted to the instrument frame 2 m above the seafloor recorded pressure, temperature, and current velocity at 1 min intervals.

Individuals were recognized as scavengers based on their observed consumption of bait (Britton & Morton 1994). Scavengers were identified to the lowest taxonomic level based on diagnostic morphological characteristics using standard keys and texts in conjunction with consultation with taxonomic specialists. For each deployment, the first arrival time,  $t_0$  (the time required for the first individual to arrive at bait after vehicle touchdown), and peak abundance,  $n_{max}$  (maximum number of a species observed in any single image throughout the deployment), were recorded for all scavenging species present. The percentage of frames in which at least 1 individual was observed,  $%_{frame}$ , was determined for *Coryphaenoides armatus* at all 3000 m deployments.

In addition to camera imagery, data were incorporated from other methods of sampling that were being conducted simultaneously during the same cruises for related projects. These included various baited hook sets and bottom trawling. Baited hook sets were not quantitative but did provide presence/absence and size data. An otter trawl (estimated door spread 6.1 m, mesh size 2.5 cm) was used at all depths and a beam trawl (mouth width 2.1 m, height 0.8 m, mesh size 2.5 cm) was used for some tows  $\geq$ 2000 m. Both gears were fished on a single warp and rigged with a pinger (Benthos) 70 m from the bridle to monitor net contact with the seafloor and 1 or 2 (depending on scope) 43 cm floats between the net and the pinger to suspend the trawl wire off the bottom. Trawl durations ranged from 15 to 60 min and depths were treated as median depth during the time that the trawl was contacting the seafloor during each haul. Animals caught via these sampling efforts provided voucher specimens to corroborate identifications designated from analysis of camera data and also provided the majority of length measurements for size analyses.

**Size analysis.** Size analysis of scavenging species Anoplopoma fimbria, Antimora microlepis, Albatrossia pectoralis, and Coryphaenoides acrolepis was performed using measurements obtained from individuals caught via trawls and baited hooks in addition to a few image-derived size estimates from camera data when available. These species were chosen because there were relatively large numbers of measurements and



Fig. 1. Baited-camera deployment sites in Monterey Bay, California, USA

because each species spanned at least 3 depths sampled during the study, thus maximizing the vertical extent of the analysis. Total length (TL) was measured for A. microlepis while fork length (FL) was measured for A. fimbria (due to forked caudal fin in this species) and pre-anal fin length (PAFL) was measured for A. pectoralis, and C. acrolepis (due to broken or incomplete caudal fins found in many individuals of these species). When possible, individuals recorded from camera observations were measured using image analysis software (ImageJ 1.38x). Details of this procedure follow Yeh & Drazen (2009) and have shown percent error of ±3.5%. A simple linear regression (Statistica v7) was applied to these data to determine significance of the relationship between fish size and depth.

**Abundance estimates.** Fish densities for Antimora microlepis and Coryphaenoides armatus (ind. km<sup>-2</sup>) were estimated using 2 independent methods, one based on trawl data and the other on camera data ( $t_0$ ) using the model proposed by Priede & Merrett (1996). Camera-based estimates utilized  $t_0$  information in the following formula (Priede & Merrett 1996):

$$N(\text{ind. km}^{-2}) = \frac{0.3849(V_{\text{f}}^{-1} + V_{\text{w}}^{-1})^2}{t_0^2}$$

where  $V_{\rm f}$  (m s<sup>-1</sup>) is the swimming velocity of the fish and  $V_{\rm w}$  (m s<sup>-1</sup>) is the current velocity averaged over the first 30 min of each deployment. Measured  $V_{\rm f}$  for *C. armatus* range from 0.0262 to 0.077 m s<sup>-1</sup> depending on location and time of year (Priede 1994, Henriques et al. 2002). A  $V_{\rm f}$  of 0.0692 m s<sup>-1</sup> obtained from the northeast Pacific in October was used in this study because this estimate was most appropriate for our data (Priede et al. 1994). Due to the lack of available  $V_{\rm f}$  data for *A. microlepis*, the measured  $V_{\rm f}$  for its congener *Anti*- mora rostrata of 0.213 m s<sup>-1</sup> (Collins et al. 1999) was used. These animals are morphologically very similar, differing only by close counts of gill filaments (Small 1981) and can be expected to have similar swimming velocities. Swimming speeds for other taxa were not available and could not be estimated in this study. Trawl and camera based density estimates from similar depths were compared using correlation analysis (Statistica v7).

# RESULTS

During 2 cruises in April and October of 2009 in Monterey Bay, 13 camera deployments were conducted California (Fig. 1). Deployment depth ranged from 105 to 3144 m, targeting 7 discrete depths: 100, 200, 500, 1000, 2000, and 3000 m. Camera bottom time ranged from 15:20 to 27:46 (hh:mm), with the average duration of data collection lasting 16:54 ( $\pm$ 2:01). Deployment information is summarized in Table 1. Additional data from 42 trawls, 3 long line, and 2 baited trap deployments were used to augment size analyses and to survey the non-scavenging fish fauna.

### Community composition and abundance

Based on observations of attraction to and consumption of bait, 25 taxa were identified as scavengers from photographic data. Identification of all scavenging fish species were confirmed with voucher specimens obtained via other methods of sampling. Multiple species of the zoarcid genus *Pachycara* were identified from trawls (*Pachycara* sp., *P. bulbiceps*, *P. gymninium*, and *P. lepinium*); however it was not possible to apply the same morphological scrutiny to individuals of this

Table 1. Baited camera deployment information. Current speed (V<sub>c</sub>) was averaged over the first 30 min of each deployment

Deployment	Latitude °N	Longitude °W	Deploy date (dd.mm.yyyy)	Deploy time (hh:mm)	Duration (hh:mm)	Depth (m)	$V_{\rm c}$ (m s <sup>-1</sup> )
APR_100m	36 48.080	121 58.454	04.04.2009	14:17	15:20	105	0.056
APR_200m	36 55.457	122 18.227	05.04.2009	12:47	19:18	209	0.065
APR_500m	36 56.633	122 22.807	07.04.2009	18:36	15:10	587	0.020
APR_1000m	36 47.187	122 17.254	08.04.2009	20:18	15:48	1010	0.094
APR_2000m	36 43.144	122 24.100	10.04.2009	13:44	24:36	2097	0.032
APR_3000m	36 34.923	122 31.196	11.04.2009	22:14	18:54	3055	0.071
OCT_100m	36 50.610	121 57.452	03.10.2009	06:45	23:28	109	0.045
OCT_200m	36 55.812	122 19.418	30.09.2009	10:41	20:56	215	0.076
OCT_500m	36 45.088	121 59.117	11.10.2009	16:51	20:18	578	0.060
OCT_1000m	36 30.654	122 08.525	10.10.2009	16:11	18:44	1116	0.056
OCT_2000m	36 45.033	122 24.195	04.10.2009	13:20	15:46	1967	0.054
OCT_3000m-1	36 33.689	122 34.684	06.10.2009	08:08	27:46	3144	0.045
OCT_3000m-2	36 36.413	122 22.786	09.10.2009	10:45	21:20	2869	0.036

genus in photographic data when trying to distinguish species. As a result, all individuals of *Pachycara* were treated as *Pachycara* spp. Similarily, photographic distinction between *Coryphaenoides acrolepis* and its congener *C. filifer* was not possible in most instances, so these species were treated as *Coryphaenoides* spp. Invertebrate identifications should remain tentative with the exception of *Neolithodes diomedea*, *Cancer magister*, *Cancer productus*, *Chionoecetes tanneri*, *Rathbunaster californicus*, and *Benthoctopus* sp. for which vouchers were obtained.

Roughly half of the scavenger assemblage was comprised of fish (12 taxa) while the other half consisted of invertebrates, most of which were decapod crabs (8 species). Other invertebrates included cephalopods, gastropods, and one echinoderm. Invertebrates dominated species richness from 100 to 200 m, while scavenger composition shifted to a fish dominated assemblage at depths >500 m. The Macrouridae was the most speciose fish family, with Albatrossia pectoralis, Coryphaenoides acrolepis, C. armatus, and C. filifer collectively spanning a range of 2000 m and accounting for 50% of all teleost taxa observed. The most abundant fish species observed were the hagfish Eptatretus deani and E. stouti, which reached peak abundances of 52 and 19 individuals, respectively (Table 2). The morid Antimora microlepis occupied the largest vertical range of any single species with a minimum

depth of occurrence of 1000 m and a maximum depth of occurrence (max depth) of 3000 m. The observation of the broad skate *Amblyraja badia* during deployment OCT\_3000m-2 extends the known max depth of this species from 2322 to 2869 m (Ormseth et al. 2008) and adds to the very few records of elasmobranchs found deeper than 2500 m (Priede et al. 2006). Decapod crabs accounted for the largest portion of the scavenger assemblage with 8 species, or 32% of the all scavenging taxa observed. Crabs were not only speciose, but highly abundant (*Paralomis manningii* and *P. verrilli*,  $n_{max} = 24$  and 20 respectively, Table 2) and distributed along the entire slope ( $\geq 1$  crab species present at every target depth).

#### Scavenger size

FL for Anoplopoma fimbria (n = 91), TL for Antimora microlepis (n = 149), and PAFL length for Albatrossia pectoralis (n = 28) and Coryphaenoides acrolepis (n = 727) are plotted against depth of capture/observation in Fig. 2. From camera imagery, 21 additional TL measurements were obtained for *A. microlepis*. Significant linear regressions (p < 0.05 between length and depth were found for all species. Anoplopoma fimbria, Antimora microlepis, and A. pectoralis increased in size with increasing depth (slope = 0.048, 0.011, 0.011,

Table 2. Scavenger peak abundance  $(n_{max})$ . ELAS: elasmobranch, MYX: myxiniform, OTHER: other invertebrates

Station	Depth				TEI	LEO	ST				ELAS	М	ΙYX			D	DEC.	APC	DD				O	ГНE	R	
	(m)	Pachycara spp.	Anaplopoma fimbria	Antimora microlepis	Albatrossia pectoralis	Coryphaenoides acrolepis	Coryphaenoides filifer	Coryphaenoides acrolepis/filifer	Coryphaenoides armatus	Spectrunculus grandis	Somniosus pacificus Amblyraja badia	Eptatretus deani	Eptatretus stouti	Cancer magister	Cancer productus	Chionoecetes tanneri	Chlorita longipes	Neolithodes diomedea	Mursia guadichaudii	Paralomis verrilli	Paralomis manningii	Benthoctopus sp.	Octopus spp.	<i>Neptunia</i> sp.	Unidentified gastropod	Rathbunaster californicus
APR100	100												19	1	9								1			5
001100	100		4										11	1	1				4				1			4
APR200	200		1										1	1	2				1				1			4
	200		1								1	22	4	2			F		1							1
APR500	500		1								1	22	1				Э						1			2
ADD1000	1000		ے 1	1	1	2					1	10	1			2							1		5	2
OCT1000	1000		1	1	1	5					1	52				5								1	J	
APR2000	2000	2	т	2	1	0		4				02								21				T		
OCT2000	2000	4		3	2			6			1							1		2		1		1		
APR3000	3000	6		1	-		3	0	11	1	1							-		-		-		-		
OCT3000-1	3000	5		2			2		11	3																
OCT3000-2	3000	4		2			1		-	4	1										24					

respectively) while *C. acrolepis* showed a slight but significant decline with depth (slope = -0.005).

# **Abundance estimation**

Fish densities were estimated independently using trawl data and  $t_0$  data for 2 fish species, Antimora microlepis and Coryphaenoides armatus (Table 3). First arrival time derived estimates were based on data from single deployments due to small sample size, while trawl derived estimates represented data averaged across multiple hauls (n = 2 to 4) conducted at similar depths and dates. Density estimates were compared between both methods and no significant correlation was found (Fig. 3). Within methods, estimates generally showed consistency and agreed well with each other for a given species and depth. For example, camera estimates for A. microlepis at 2000 m in April and October (1412 and 1615 ind. km<sup>-2</sup>, respectively) agreed well with each other as did trawl estimates for C. armatus at 3000 m in April and October (720 and 801 ind. km<sup>-2</sup>, respectively).

## Scavenging as a function of depth

The frequency of scavenging as a feeding mode was evaluated by comparing the number of scavenging fish species to the total number of fish species for each target depth. Scavenging fish species were designated as such based on camera observations. The total number of fish species was calculated as the cumulative sum of all distinct species observed across the suite of sampling methods used in this study. The resulting ratio depicts the percentage of the fish taxa that is com-

Table 3. Antimora microlepis and Coryphaeonoides armatus. Comparison of estimated fish density (ind.  $\rm km^{-2}$ ) based on camera and trawl data. Camera estimates utilize first arrival ( $t_0$ ) data from single deployments while trawl estimates display averages  $\pm$  SD, number of samples in parentheses

	t <sub>0</sub> (min)	<u> </u>	sity (ind. km <sup>-2</sup> ) Trawl (no. samples)
Antimora mi	crolepis		
APR 1000	(862)	0	395 ± 287 (4)
OCT 1000	(124)	4	$810 \pm 326$ (4)
APR 2000	(10)	1412	$418 \pm 214$ (3)
OCT 2000	(6)	1615	477 ± 344 (4)
APR 3000	(36)	29	$0 \pm 0$ (2)
OCT 3000	(40)	48	$0 \pm 0$ (3)
Coryphaeno	ides armatus		
APR 3000	(20)	217	720 ± 727 (2)
OCT 3000	(14)	726	801 ± 836 (3)



Fig. 2. Fish length (cm) vs. depth of capture or observation for (a) Anoplopoma fimbria, (b) Antimora microlepis, (c) Albatrossia pectoralis, and (d) Coryphaenoides acrolepis. ×: trawl caught; +: baited individuals; FL: fork length; TL: total length; PAFL: pre-anal fin length



Fig. 3. Estimated fish densities, trawls vs. camera

prised of scavengers (Fig. 4). A steady increase from shelf to abyssal depths in the ratio between the number of scavenging fish species vs. non-scavenging fish species is apparent. At 100 m, only 2% of all fishes were scavengers, while at 3000 m, 46% of all fishes were scavengers. In general, a decline was seen in the total number of fish species found with increasing depth. When scavenging fish species were considered separately, the opposite trend was displayed—scavenging fish species richness increased with increasing depth.

Macrourid bait and scavenging behavior

Coryphaenoides armatus was found in high abun-

dances at 3000 m in this study. Camera data (deploy-

ments APR\_3000m and OCT\_3000m-1, Table 2) and

trawl data (Table 3) from different times in the year

demonstrate the omnipresence of this cosmopolitan scavenger in Monterey Bay. During baited-camera deployment OCT\_3000m-2, bait was switched from the standard bait in this study, Chanos chanos (~2 kg), to one whole C. armatus of similar size. A complete absence of C. armatus was observed during this 21 h deployment (Fig. 5a). Both deployments using standard bait (Fig. 5b, c) exhibited high peak abundances, short first arrival times, and high percentages of frames with at least 1 individual in the field of view (Table 4). The 3 other non-macrourid scavenging fish taxa present at 3000 m deployments using standard bait appeared to be unaffected in terms of  $n_{\text{max}}$  (Table 2) by the switch to macrourid bait. Similarly, no trends were detectable in  $t_0$  for these species between bait types (A. microlepis 36 and 40 vs. 22 min; S. grandis 522 and 36 vs. 40 min; Pachycara sp. 366 and 80 vs. 478 min). However, C. filifer, the other macrourid at this depth did have a lower  $n_{max}$  (Table 2) and a higher first arrival time (114 min) when macrourid bait was used compared to the other 3000 m deployments (40 and 28 min). Paralomis manningii was only found at OCT\_3000m-2 during this study and in high abundance  $(n_{\text{max}} = 24)$ .

## DISCUSSION

#### Validity of abundance estimates

# Our comparison of camera- and trawl-derived abundance estimates showed no correlation (Fig. 3). It is possible that the swimming speeds used here do not accurately reflect actual speeds of fishes in this study. To address this possibility, the full range of measured $V_{\rm fs}$ for *Coryphaenoides armatus* was considered (data



Fig. 4. Numbers of fish species. Scavenging (grey) vs. non-scavenging species (black) for targeted depths





Fig. 5. Coryphaenoides armatus. Images from 3000 m camera deployments at time of peak abundance  $(n_{max})$  using (A,B) Chanos chanos as bait and (C) C. armatus as bait

not presented) but still no correlation was found. This analysis was hindered by sample size; for each depth and time of year analyzed, data from only single camera deployments were available to compare to the trawl data. Additionally, trawl-derived fish density Table 4. Coryphaeonides armatus. Abundance data for 3000 m deployments.  $n_{max}$ : peak abundance; %frames: percentage of frames in which at least 1 individual was observed;  $t_0$ : time of first arrival; na: not applicable

	n <sub>max</sub> (ind.)	% <sub>frames</sub> (%)	t <sub>0</sub> (min)
APR_3000m	11	50	12
OCT_3000m-1	12	83	14
OCT_3000m-2	0	0	na

showed high variability for temporally and spatially similar hauls as evidenced by standard deviations on the same order of magnitude as the averages themselves (Table 3). However, given that no other statistical comparison of these types of estimates exists, our efforts offer useful information in evaluating a general model that has rarely been tested. The results do demonstrate precision within methods, evidenced by consistent and reproducible results.

Priede & Merrett (1996) did find correlation between baited camera and trawl methods of density estimation, however, in their statistical treatment of the data they compared the quantity  $t_0^{-2}$  against trawl data as opposed to comparing the output of the model itself to the trawl data. We found no such correlation (data not shown). This approach eliminates variation that may have arisen due to differences in current velocity, which is an inherent parameter of their model. Furthermore, trawl and camera data in their study were averaged over a large latitudinal range (up to 18°), and homogeneity in abundance is unlikely to hold over such a large area. When these considerations are taken into account, disagreement between studies is explicable. Farnsworth et al. (2007) performed an in depth evaluation of abundance estimation based on first arrival time and concluded this method is highly uncertain, but this finding was based on a purely theoretical approach. Our results support their finding with empirical data.

## Scavenging behavior and depth

While depth-related patterns in the size, abundance, and vertical zonation of scavengers have received significant attention, the prevalence of scavenging behavior itself with respect to depth has rarely been documented. Multiple collection methods employed in this study allowed for comprehensive sampling of the demersal fish fauna of the California slope as well as the ability to discern between scavenging and nonscavenging taxa. The progressive transition of 2 to 46% scavengers observed from 100 to 3000 m (Fig. 4) suggests an increasing importance of carrion in the diets of demersal fishes and a shift to an opportunistic foraging strategy at deeper portions of continental margins. This finding contrasts with observations in the NE Atlantic where Priede et al. (2010) found scavenging fish to comprise a constant proportion of the fish fauna (22.7%) from 240 to 4965 m. This result was an average across depths. If the data presented in Fig. 4 are averaged, the resulting value of 22% would be very close to that presented by Priede et al (2010). It is interesting to note that at depths <1000 m, the data in Priede et al. (2010) yield percentages of <10%, similar to our own findings. The real difference in trends is that the proportion of scavengers below 1000 m change very little with depth in the North Atlantic but the proportion increases in our results. The fauna in the Priede et al. (2010) study come from a larger sampling effort than ours. It is possible that additional species of both scavenging and non-scavenging taxa would be sampled off California with more deployments, thus altering our results.

A depth-related increase in the proportion of scavenging fish follows trends in food availability. Many demersal fishes consume benthic and demersal invertebrates (Pearcy & Amber 1974, Macpherson & Roel 1987, Takahashi & Iwami 1997, Drazen et al. 2001). Benthic biomass and abundance have been found to decline exponentially with depth (Rowe et al. 1974, Gage & Tyler 1985, Lampitt et al. 1986) along the continental slopes of many regions, and as a result food supply is diminished for animals that feed on the benthos. Demersal fish occupying shelf and upper slope depths also consume large proportions of vertically migrating zooplankton and micronekton (Mauchline & Gordon 1991, Drazen et al. 2001, Yamamura & Inada 2001, Chae et al. 2008). With increasing distance from shore along continental margins, vertical migrators become less available as a source of prey as water depth exceeds the maximum depth of the deep scattering layer. With limited alternative food sources, animals may broaden their trophic strategies and adopt scavenging to at least partially fulfill their energetic demands. The principal nutritional source for macrourids on the NE Pacific abyssal plain has been suggested to be carrion (Drazen et al. 2008, 2009), supporting this line of reasoning.

#### Size trends with depth

Our findings of 'bigger-deeper' trends for Albatrossia pectoralis, Anoplopoma fimbria, and Antimora microlepis but not for Coryphaenoides acrolepis reinforce the notion that size-depth trends should be evaluated on a species by species basis. The 'bigger-

deeper' trend has been shown for Anoplopoma fimbria in previous studies and is well established for this species. Results from groundfish surveys (Lauth 1999) show this trend independently for males and females and for both sexes combined. Temporal stability has been demonstrated for 2 decades (1988 to present) and for multiple regions of the US west coast (Lauth 1999, Jacobson et al. 2001). Likewise, A. microlepis has been shown to follow the 'bigger-deeper' trend in the Northwest Pacific off the Kamchatka peninsula, where individuals increased in both TL and weight from depths of 200 to 1700 m (Orlov & Abramov 2002 and references within). Its closely related congener from the Atlantic, Antimora rostrata, has also displayed the same trend (Collins et al. 2005). For A. pectoralis, the 'biggerdeeper' trend has also been reported in the Kuril Islands (Orlov & Tokranov 2008) but in the Gulf of Alaska and eastern Bering Sea males show no size difference with depth and females are smaller at greater depths (Clausen 2008). The reasons for the differences between California and the Bering Sea are unclear. It seems logical that the trends in the Bering Sea are related to reproduction but the regional differences in the patterns might also be related to differing temperature profiles.

In contrast to these species, *Coryphaenoides acrolepis* displayed a weak decrease in size with increasing water depth (m = -0.005, R<sup>2</sup> = 0.117; Fig. 2). Size decrease with depth has been reported for individual species (Macpherson & Duarte 1991, Yeh & Drazen 2009) and for fish assemblages as a whole (Stefenescu et al. 1992). Whether the results presented here are truly evidence of a 'smaller-deeper' trend is questionable. The slightly negative slope may be a result of net avoidance of this species at greater depths or other unexplained sampling biases. What is undeniable is the absence of a 'bigger-deeper' trend for this species. The lack of any size-depth relation was also noted for *C. acrolepis* collected off Oregon (Stein & Pearcy 1982).

'Bigger-deeper' phenomena have been attributed to migration to deeper water during ontogeny (Jacobson et al. 2001), but reasons for why this would be evolutionary favorable remain unclear. Macpherson & Duarte (1991) proposed that ontogenetic migration would be advantageous because deeper living animals would have lower metabolic rates and increased longevity due to depressed temperatures, these depressed temperatures being intolerable or lethal to smaller, younger individuals. However, 'biggerdeeper' trends have been demonstrated in high latitudes where temperature gradients are small and thermoclines not pronounced (Orlov & Abramov 2002 and references within). Collins et al. (2005) surmised that larger size is required at greater depths only in scavenging fishes to permit greater swimming speeds and lower metabolic rates to facilitate foraging on the carrion of food falls, which become more sporadic with increasing depth. All the species we examined are scavengers as evidenced from baited-camera observations, even C. acrolepis which did not exhibit the bigger-deeper pattern. Yet, 'bigger-deeper' trends have been shown for the flatfish Microstomus pacificus and rockfish Sebastalobus alascanus (Jacobson & Hunter 1993, Jacobson & Vetter 1996), both of which were abundant in the study area and in the trawls but were not found to scavenge based on camera observations. Foraging mode does not appear to be as important a driver of size-depth patterns as it is in the North Atlantic (Collins et al. 2005). Instead, off California there is an oxygen minimum zone from ~600 to 1000 m (Levin 2003) which may alter patterns or curtail others in some species. For instance the ontogenetic migration in dover sole has been attributed to adults finding a habitat with low predation pressure (Hunter et al. 1990). It seems, then, that size-depth trends may not be explained by a single theory and perhaps a combination of ecological and physiological drivers are at play which vary regionally.

### Macrourid aversion to conspecific bait

Coryphaenoides armatus were not attracted to the camera when a conspecific was used as bait. The presence of C. armatus in high numbers at camera deployments using standard baits (APR\_3000m and OCT\_ 3000m) and in trawl catches in the area (Table 4), suggests that its absence is not coincidental or the result of a lack of animals in the study area. It is possible that differences in tissue composition and biochemistry between bait types vary their resulting odor's detectability or attractiveness. Antimora microlepis, Pachycara spp., and Spectrunculus grandis all reached  $n_{\rm max}$  or near maximum values found in this study (Table 2) when macrourid bait was used, implying odor plume 'strength' was not substantially reduced between bait types. For C. armatus it is unlikely that diminished detection ability for macrourid bait caused its absence. This species has demonstrated attraction to a wide range of bait from cetacean carcasses (Kemp et al. 2006) to spinach (Jeffreys et al. 2010), the latter suggesting an acute sense of olfaction in this species which would not likely preclude the odor plumes of dead macrourids. Lampitt et al. (1983) used C. armatus as bait on the North Atlantic abyssal plain and noted very few rattails but many lysianassid amphipods and liparid fishes. Barry & Drazen (2007) observed similar aversion of C. armatus to a dead conspecific and hypothesized that macrourids avoid dead congeners or

conspecifics because they may indicate dangerous conditions. It is also interesting that *C. filifer*, the other macrourid observed at 3000 m, had a marginally lower  $n_{\rm max}$  and higher first arrival time when *C. armatus* was used as bait. This species was never present in large numbers at bait but it is possible that the odor of a congeneric resulting in some aversion. Our results strengthen this idea and suggest that more experiments should be conducted which evaluate the response of scavengers to various types of bait.

Other scavengers observed at 3000 m appeared unaffected by the bait switch with the exception of the lithodid crab, *Paramolis manningii*, which was observed only at macrourid bait. Crabs in general displayed patchiness in this study (Table 2) and were not consistently caught in trawls (J. C. Drazen unpubl. data), which could explain these results. However, it is also possible that the crabs are normally deterred by the presence of more active scavenging rattails either due to competition or predation.

Nearly 40 yr have passed since the first baited camera experiments were performed off southern California. We compared fish density estimates derived from baited camera data to those derived from trawl data with statistical rigor and no correlation was found. Baited cameras are certainly useful tools in examining scavenger ecology - many animals which avoid trawls are only observed remotely. However, further investigation is recommended before abundance estimates from this technique can be interpreted with confidence. From the community perspective, our results show changes in the dominant scavengers with depth from crabs and hagfishes to macrourids and other fishes at greater depths. The proportion of fishes that were scavengers increased from 2 to 46% with depth unlike data for the North Atlantic, in which the proportion of scavengers changed little with depth. In addition, our findings have contributed more information to the size-depth conundrum in fish. Contrary to recent hypotheses suggesting that 'bigger-deeper' trends are determined by foraging strategy in the North Atlantic, our North Pacific data suggest a global explanation may be more complicated. The basin to basin differences highlight the need to conduct more baited camera studies in other parts of the world so that we can derive a better understanding of scavenger ecology globally. Finally, bait type was shown to affect scavengers differently, with complete avoidance of the odor of conspecifics, highlighting the need to use different bait types to learn more about the behavior and ecology of these species.

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